

# **STEEL MANUFACTURING MODEL**

Process Modeling and Simulation

## **Steel Manufacturing**

Professor. Dr. Yilmaz Uygun

Group 2: Hala Abuhassan, Alexandra Gkragakopoulou, Joelle Karadsheh, Nada Martinovic

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## Introduction (Alexandra)

The goal of this assignment is to simulate the manufacturing of steel. Steel is mainly used while constructing buildings, infrastructure, tools, ships, automobiles, machines, appliances and weapons. The main steps that are involved in the manufacturing of steel are: melting of scrap, degassing, compact strip production, cold strip milling. Our report consists of a 2D animation, graphs and diagrams for total production, slab processing time, number of slabs and coils produced, and a graph showing different products. We also discuss important parameters of the system, we run an optimization experiment where we change the input rate, a maintenance model and develop a system dynamics model.

## Question 1 (Joelle and Nada)

The model below shows the steel manufacturing plant. Steel is manufactured through different processes. The steel plant produces galvanized and galvannealed sheets, cold rolled fully processed sheets, hot rolled plates, and cold rolled full hard sheets).

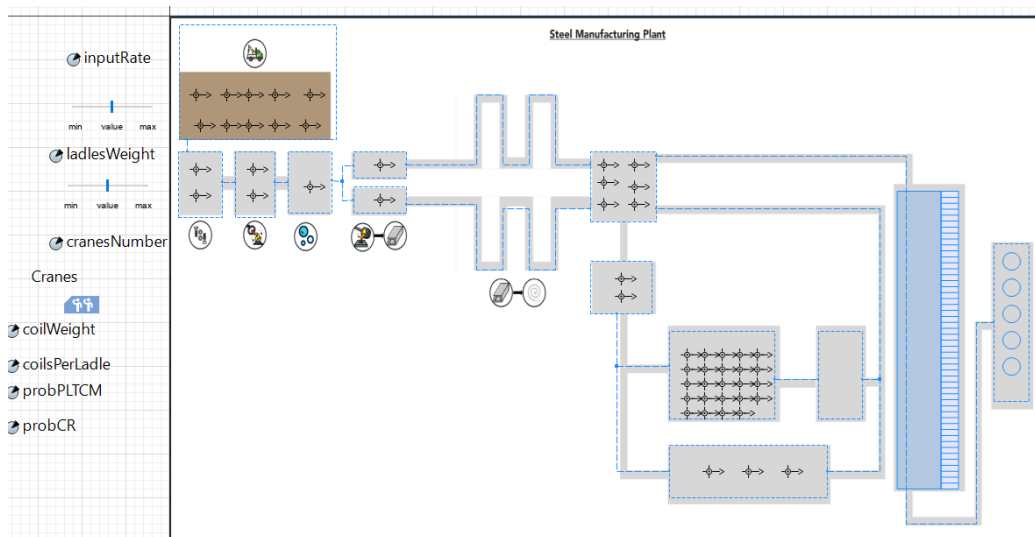


Fig.1 Steel Plant

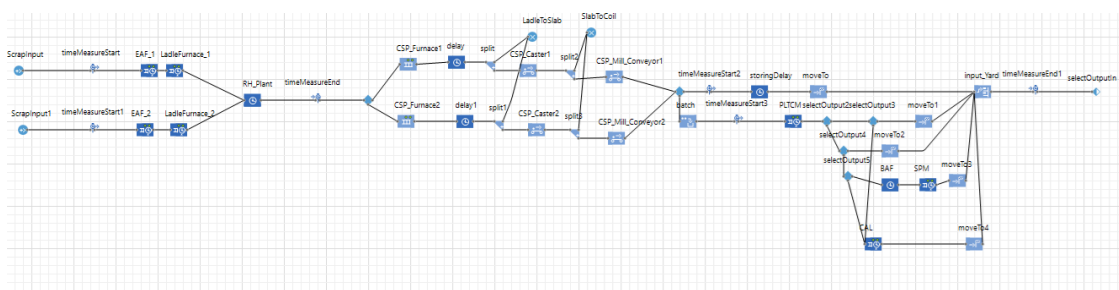


Fig.2 Production flow

## Question 2 (Hala)

### First graph: Total production

In order to visualize the total production at the steel plant we added a time plot graph and named it “Total Production”. We used a time plot specifically to show us the total production over time. It is very important to note that the total production also considers the amount of slab produced in earlier stages as well as coil production, hence our total production consists of (steel slabs, Coil, hot rolled HR, cold rolled hard sheet, GIGA, CRFP, HRP, CRFH).

Total production = amount produced \* LadlesWeight

The amount of each product produced is taken from the output. Hence, in the time plot and under “value” we add up all the outputs for all the products and then we multiply them with the ladles weight which is in tons. The graph on the right shows an increasing graph because as more time passes we are producing more products.

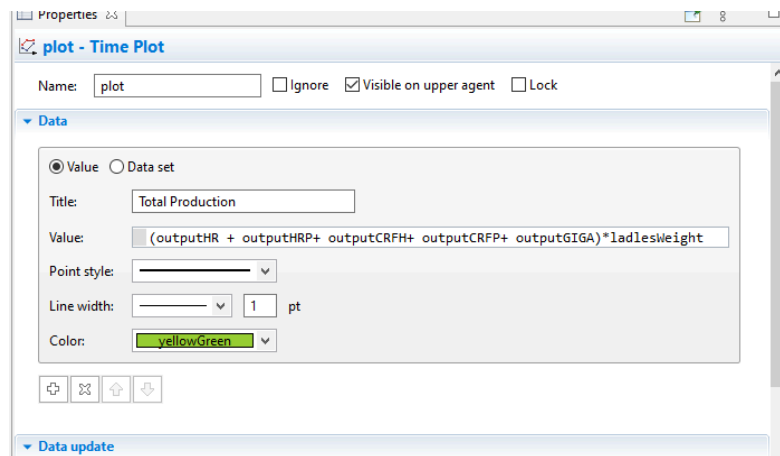


Fig.3 Time plot properties

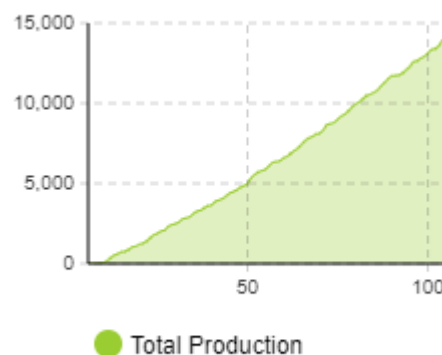
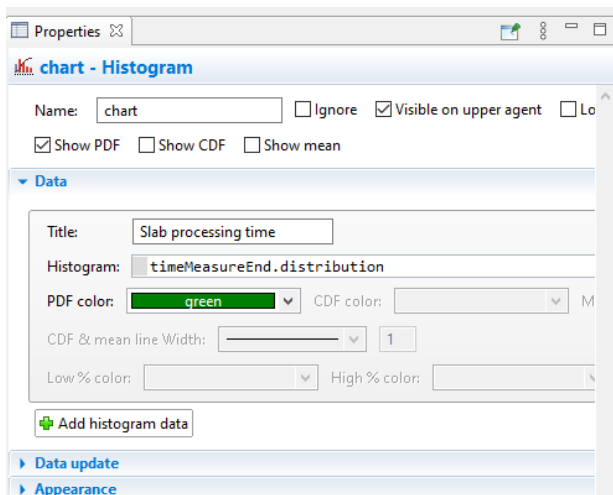
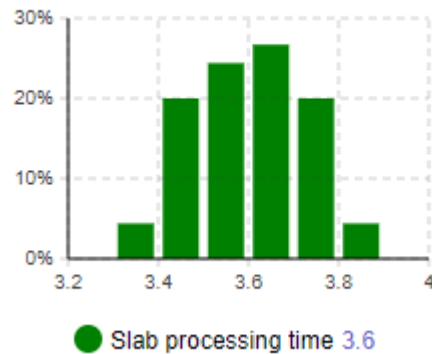


Fig.4 Amount produced in tons over time

**Second graph:** It is for the slab processing time, for this we need to consider the timeMeasureEnd as it measures the time. We use the histogram graph and change the properties in it. We put “timeMeasureEnd.distribution” and we name the graph “Slab processing time”. Finally, we notice that the mean slab processing time is 3.6.

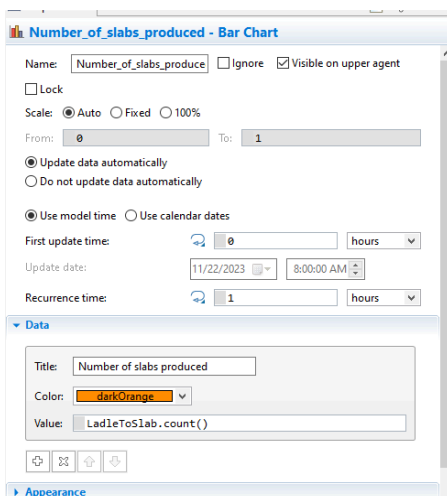
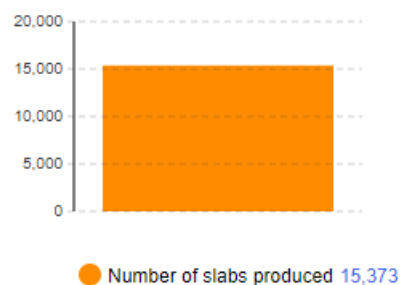


**Fig.5 Histogram Properties**

**Fig.6 Distribution slab processing time**

**Third graph: Number of slabs produced**

First, we create a bar chart and assign it to the name “Number of slabs produced” Then we set the value in the data to “LadleToSlab,count()” This will count the slabs at the sink because that is the total amount of steel slabs produced. The number of steel slabs produced is 15,373 and that is the amount reached when the max number of agents is reached.



**Fig .7 Bar chart properties**

**Fig. 8 Total amount of slabs produced**

#### Fourth graph: Number of coils produced

we add another bar chart. This time we want to count the number of coils produced. Hence, we consider the sink “SlabToCoil” where the total amount of coil produced is collected. We use a count function to measure the total number of coils produced in this steel plant. We notice that the total amount is 15,364.

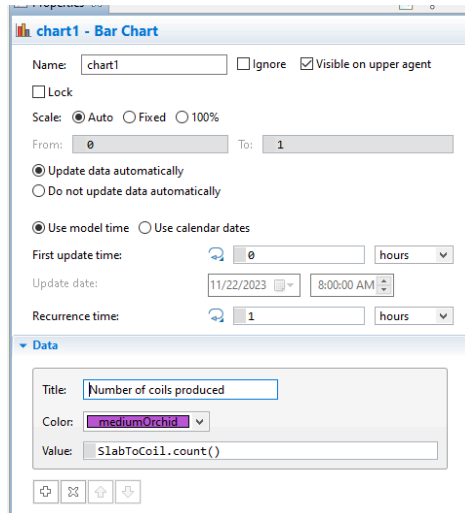


Fig.9 Bar chart properties

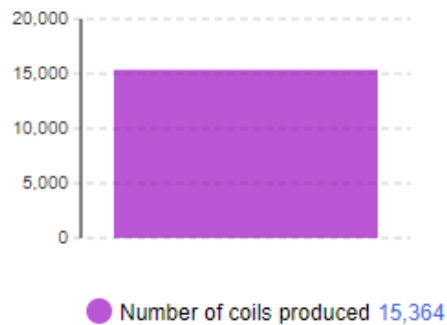


Fig.10 Bar Chart for total amount of coils produced

### Fifth graph: Variations of products at the plant

The given flow chart in the assignment shows the total amount of products produced at the steel plant. However, it is still better to visualize them. Therefore, we added a bar chart and we added 5 products (HR,HRP,CRFH,CRFP,GIGA). Each has a different color to help distinguish between them, the values are different according to the product produced. Notice how at the beginning of the simulation, the amount of products produced is 0 since there is a process that needs to happen before it starts producing the products, but as they move from the conveyor, the products will start to show in the graph and the graph displays the following numbers.

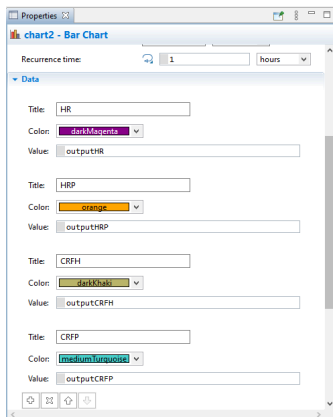


Fig.11 Bar Chart Properties

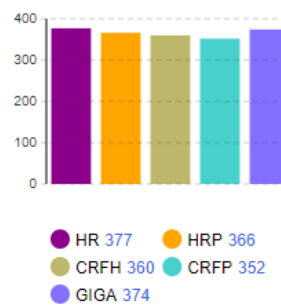


Fig.12 Different products at the plant

### Question 3 (Joelle)

To show the changes in different stages and highlight the different results from various processes, we included two statecharts in this model: one for the ladle and another for the coil.

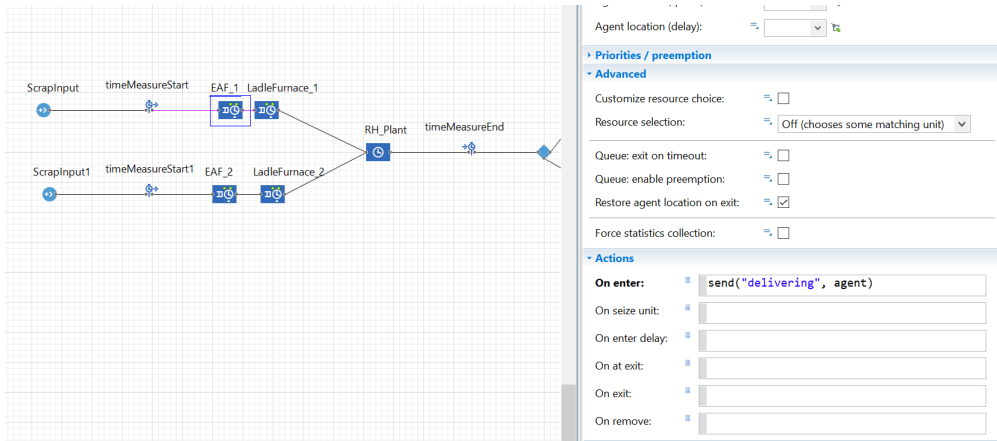
#### 1. Ladle state chart

To enhance the ladle diagram in our model, we introduced an oval shape at the top. This oval alternates between the colors blue, cyan, dodger blue and yellow Green, representing different phases the ladle undergoes. Our statechart outlines four main states: Delivery, Scrap, Molten Steel, and Post-Degassing, with transitions between these states initiated by specific messages.

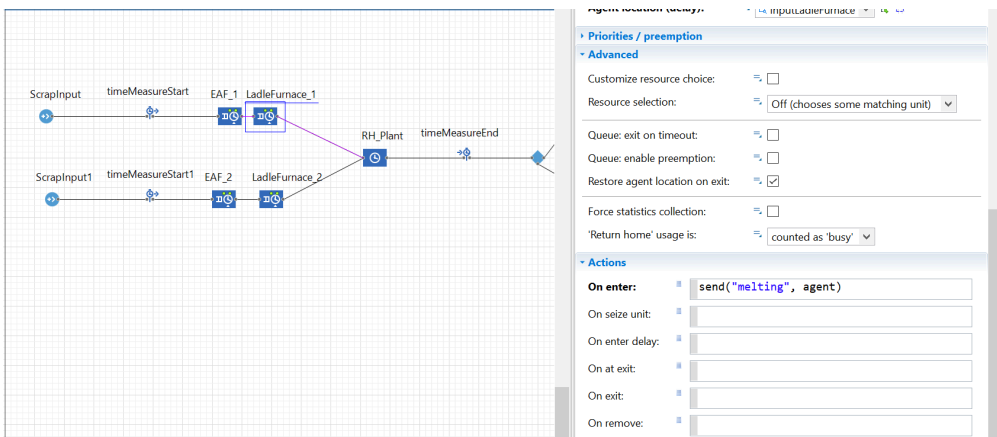
The statechart starts in the Delivery state, moving to Scrap upon receiving the "delivering" message. This transition is programmed in the EAF\_1 and EAF\_2 blocks, where the function `send("delivering", agent)` is activated in the On Enter section. Similarly, the Molten Steel state is initiated by the "melting" message from the LadleFurnace\_1 and LadleFurnace\_2 blocks.

The final phase, Post-Degassing, is reached from the Molten Steel state through a transition triggered by the "degassing" message. This message is sent by the RH\_Plant block using the function `send("degassing", agent)` in its On Enter section.

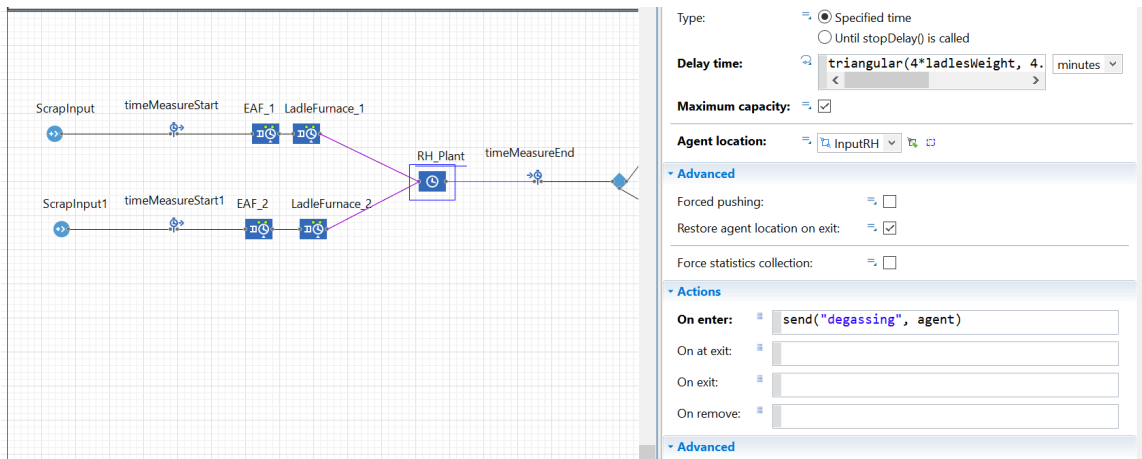
To visually track these transitions, we implemented the `oval.setFillColor(Color)` function in the Entry and Exit actions of each state. This ensures the oval changes color corresponding to each state transition, vividly illustrating the progress through each step of the process.



**Fig.13 EAF\_1 and EAF\_2 actions**



**Fig.14 LadleFurnace\_1 action**



**Fig.15 RH\_Plant action**

**transition - Transition**

Name:   Show name  Ignore

Triggered by:

Message type:

Fire transition:  Unconditionally  
 On particular message  
 If expression is true

Message:

Action:

Guard:

**Description**

**transition1 - Transition**

Name:   Show name  Ignore

Triggered by:

Message type:

Fire transition:  Unconditionally  
 On particular message  
 If expression is true

Message:

Action:

Guard:

**Description**

**Fig 16+17 Transition**

**transition - Transition**

Name:   Show name  Ignore

Triggered by:

Message type:

Fire transition:  Unconditionally  
 On particular message  
 If expression is true

Message:

Action:

Guard:

**Description**

**transition2 - Transition**

Name:   Show name  Ignore

Triggered by:

Message type:

Fire transition:  Unconditionally  
 On particular message  
 If expression is true

Message:

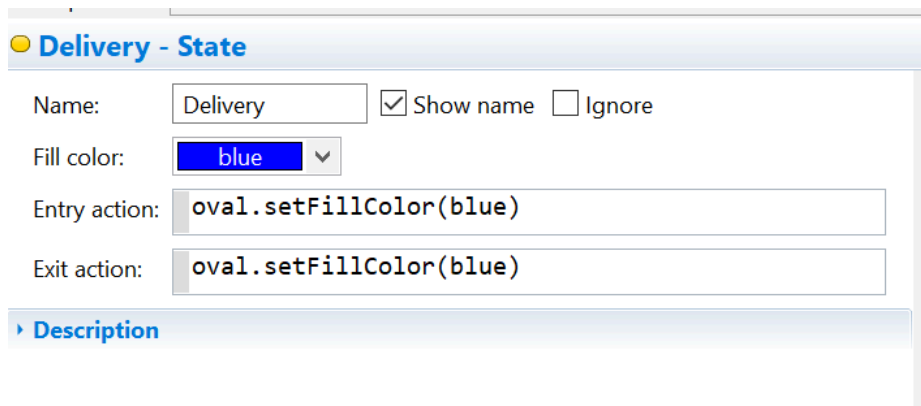
Action:

Guard:

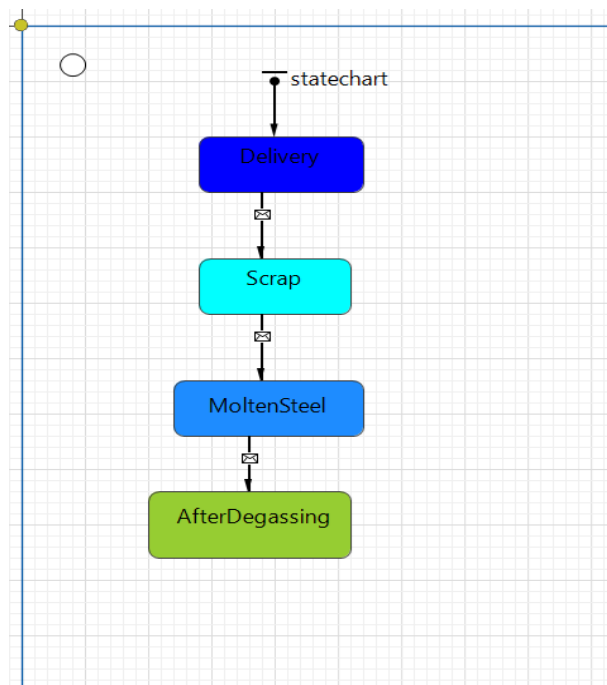
**Description**

**Fig 17+18 Transitions**





**Fig.19 Example of State**



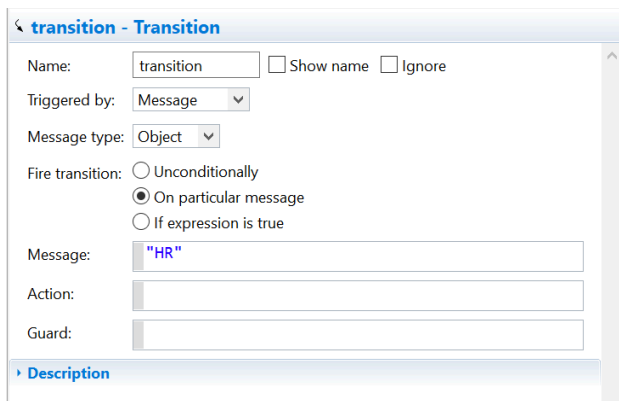
**Fig.20 state chart**

## 2. Coil state chart

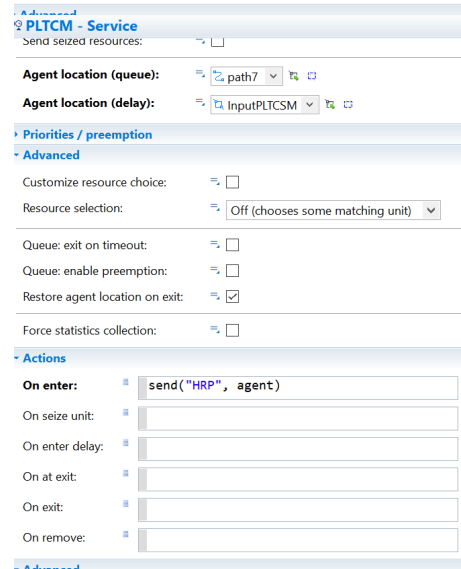
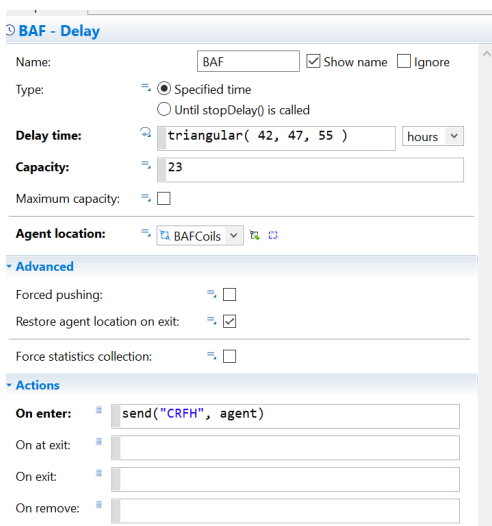
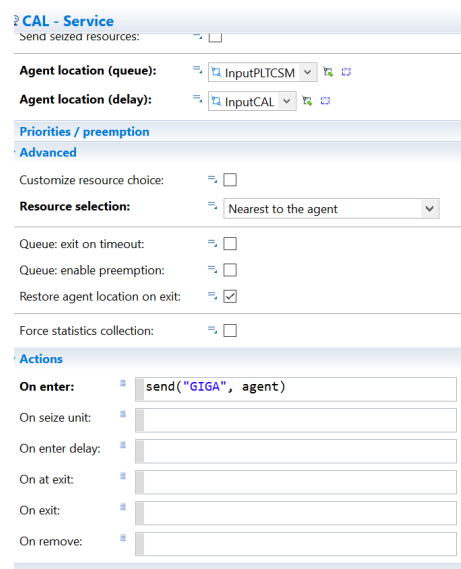
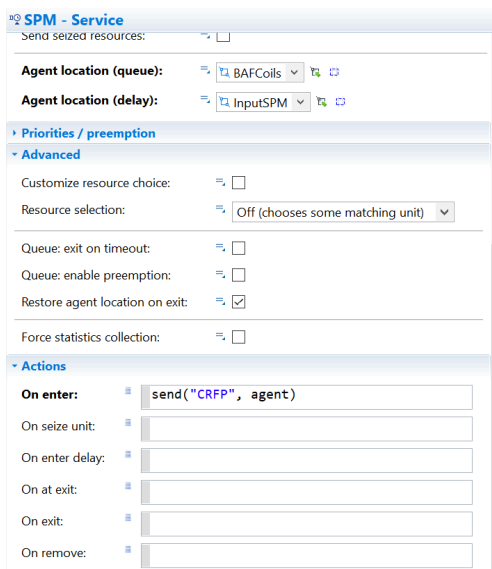
Here, we are adding colors to the 3D boxes in our model using a statechart with 6 states and 5 transitions. These transitions are activated by 'String' type messages, set up so that the Fire transition responds to specific messages. The statechart begins at the "Coils" state and includes two transitions activated by messages, leading to either the HR or HRP states. The transition between "Coils" and "HR" is a message and in particular message "HR", As for the transition between "Coils" and "HRP" it is also a message and in particular message "HRP". As for the main chart I put "send("HR", agent)" on enter action in storingDelay. We added "send("HRP", agent)" on enter action in PLTCM. From HRP, transitions lead to either GIGA or CRFH states. For the transition between HRP and GIGA it is a message with one particular message "GIGA" and the same logic for the transition between HRP and CRFH

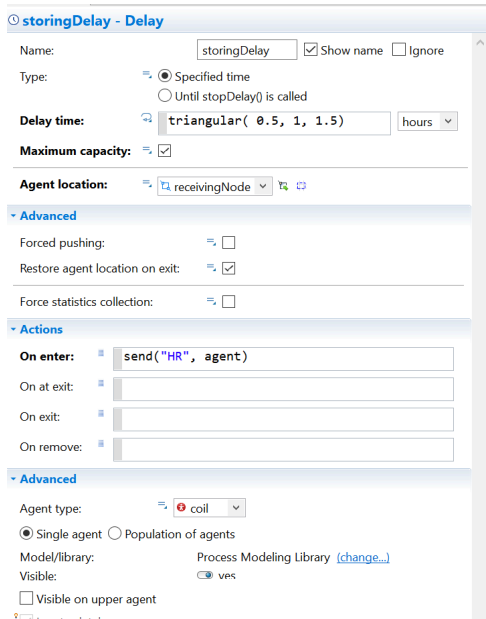
with the message being “CRFH”. As for the main chart I put “send(“GIGA”, agent)” on enter action in CAL and I added “send(“CRFH”, agent)” on enter action in BAF. The final transition moves from CRFH to CRFP with a message transition of “CRFP” and “send(“CRFP”, agent)” as an on enter action in SPM.

The statechart uses colors like powderBlue,mediumPurple,orchid,salmon,lightGrey and yellowGreen. We apply these colors using the `shapeBox.setFill(Color)` function in each state's Entry action. This setup ensures that the box colors change dynamically, reflecting the current process stage of the steel and differentiating various outputs by color.

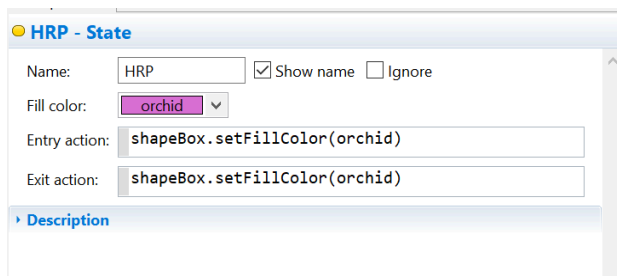


**Fig.21 Transition example**

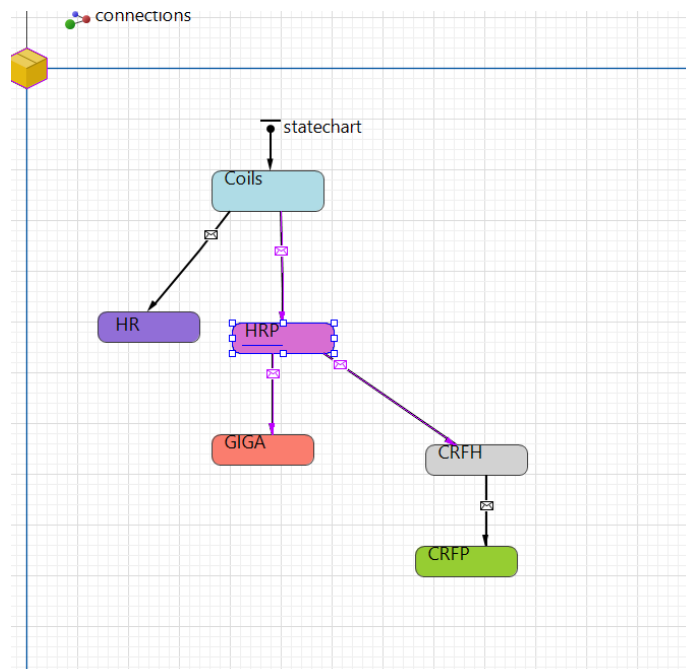




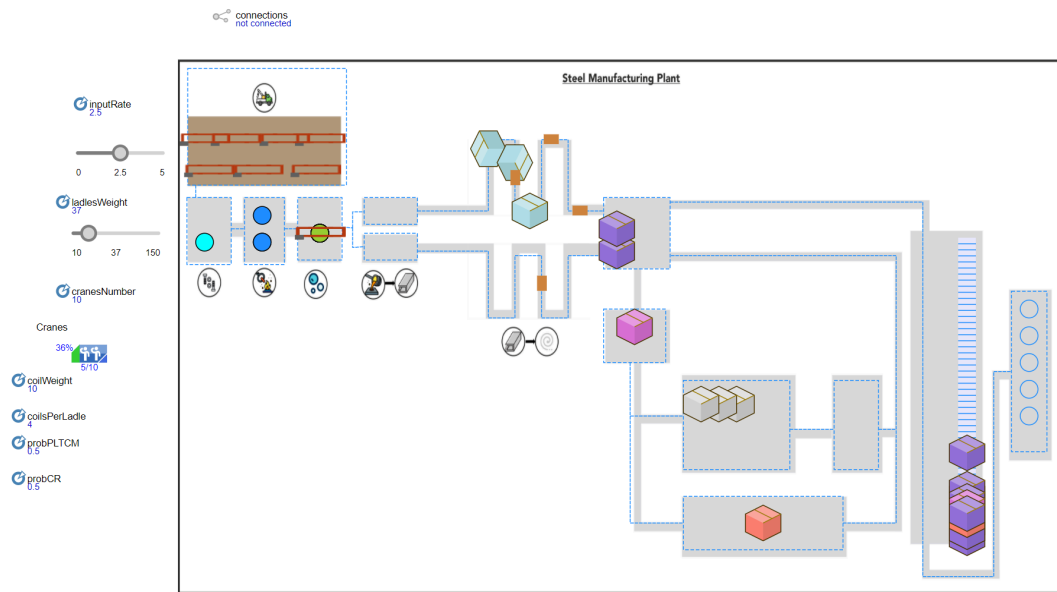
**Figs.22 till Figs 26 are all on enter actions**



**Fig.27 HRP state example**



**Fig.28 State charts**



**Fig.29 Simulation running**

#### Question 4 (Nada)

There are seven essential parameters in our model. They are all represented in the following pictures.

1. inputRate - with a default value 2.5 and type double. It controls the rate at which the scrap metal is entering the model and is directly connected to the production rate.
2. cranesNumber- represents the total number of cranes in the model, with the value of 10
3. ladleWeight- represents the ladle's weight. The default value is 40.
4. coilWeight- weight of coil has a default value of 10.
5. coilsPerLadle - the amount of coils made per one ladle. The type is double and is connected to  $\text{ladlesWeight} / \text{coilWeight}$ .
6. probPLTCM - represents the probability of going to the production of hot rolled steel coils and the rest goes to cold mill. It is also type double and has 0.5 as a default value.
7. probCR-by default it is 0.5 probability and determines the specific selectOutput which shows which output is going to be produced.

**inputRate - Parameter**

Name:   Show name  Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**Value editor**

Label:

Control type:

Hide conditions:

Parameter	Condition	Value

**Advanced**

Static  Dynamic  Action

System dynamics units:

Save in snapshot

On change:

**Description**

**Fig.30 Input Rate**

**ladlesWeight - Parameter**

Name:   Show name  Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**Value editor**

Label:

Control type:

Hide conditions:

Parameter	Condition	Value

**Advanced**

Static  Dynamic  Action

System dynamics units:

Save in snapshot

On change:

**Description**

**Fig.31 Ladles Weight**

**probCR - Parameter**

Name:   Show name  Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**Value editor**

Label:

Control type:

Hide conditions:

Parameter	Condition	Value

**Advanced**

Static  Dynamic  Action

System dynamics units:

Save in snapshot

On change:

**Description**

**Fig.32 ProbCR**

**coilsPerLadle - Parameter**

Name:   Show name  Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**Value editor**

Label:

Control type:

Hide conditions:

Parameter	Condition	Value

**Advanced**

Static  Dynamic  Action

System dynamics units:

Save in snapshot

On change:

**Description**

**Fig.33 Coils Per Ladle**

**probPLTCM - Parameter**

Name:   Show name  Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**Value editor**

Label:

Control type:

Hide conditions:

Parameter	Condition	Value

**Advanced**

Static  Dynamic  Action

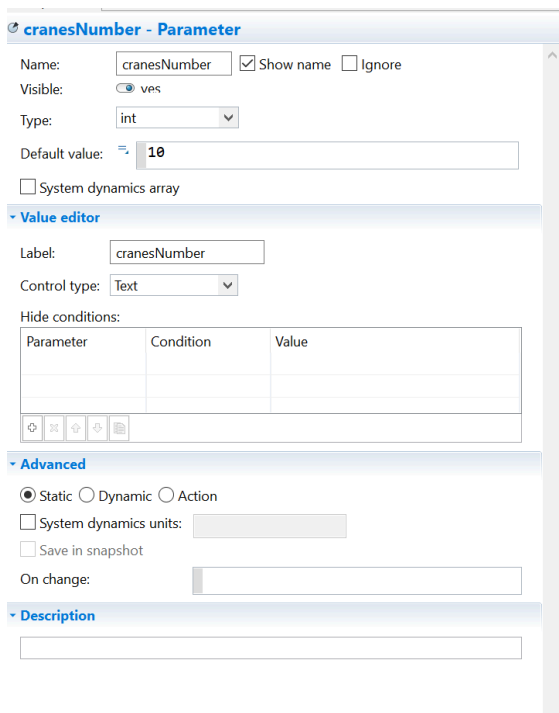
System dynamics units:

Save in snapshot

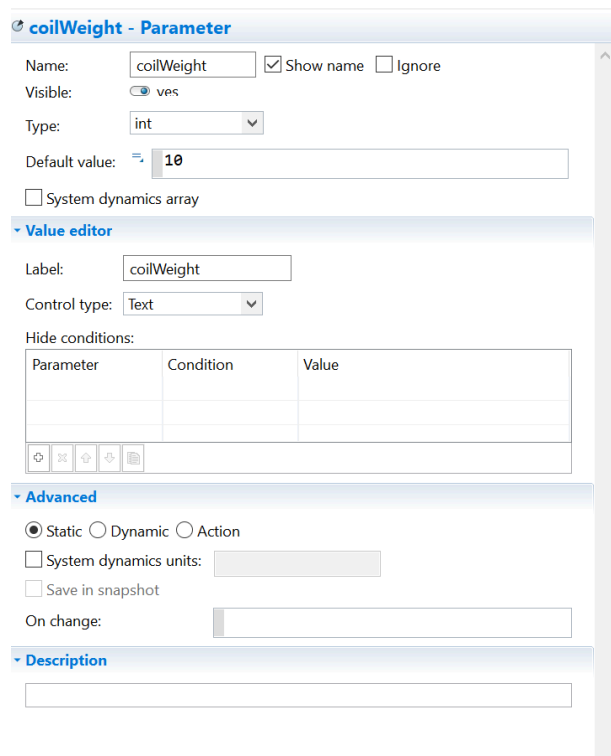
On change:

**Description**

**Fig.34 probPLTCM**



**Fig.36 Cranes Number**



**Fig.35 Coil Weight**

**Question 5 (Alexandra)**

For this task, we will try to make an optimization of our model to increase the production rate by changing the input rate. We create a new model- optimization experiment and set the number of iterations to 500. In the main, we create a new variable ‘totalProduction’ and in the function body we enter: return (outputHR + 2\*(outputHRP + outputCRFH + outputCRFP + outputGIGA))\*ladlesWeight; Then, in the optimization we set the objective function to root.totalProduction() and select maximize.

**Fig.37 totalProduction Function**

**totalProduction - Function**

Name: totalProduction  Show name  Ignore  
 Visible:  no  
 Just action (returns nothing)  
 Returns value  
 Type: double

**Arguments**

Name	Type

**Function body**

```
return (outputHR + 2*(outputHRP + outputCRFH + outputCRFP + outputGIGA))*ladlesWeight;
```

**Advanced**  
**Description**

**Properties Optimization1 - Optimization Experiment**

Name: Optimization1  Ignore  
 Top-level agent: Main  
 Optimization engine: Genetic  
 Objective:  minimize  maximize  
 root.totalProduction()

Number of iterations  
 Fixed: 500  
 Infinite  
 Maximum available memory: 512 Mb  
 Create default UI

**Parameters**

Parameters:

Parameter	Type	Value			
		Min	Max	Step	Su...ed
inputRate	discrete	0.5	10	0.5	
ladle...ight	fixed	40			
cran...ber	fixed	10			
coilWeight	fixed	10			
coils...Ladle	fixed	ladlesWeight/coilWeight			
pro...TCM	fixed	0.5			
probCR	fixed	0.5			
BadQuality	fixed	0.05			
reworkTime	fixed	3			
MTTF	fixed	5			
MTTR	fixed	1			
MTTM	fixed	4			
numb...nes	fixed	10			

**Model time**

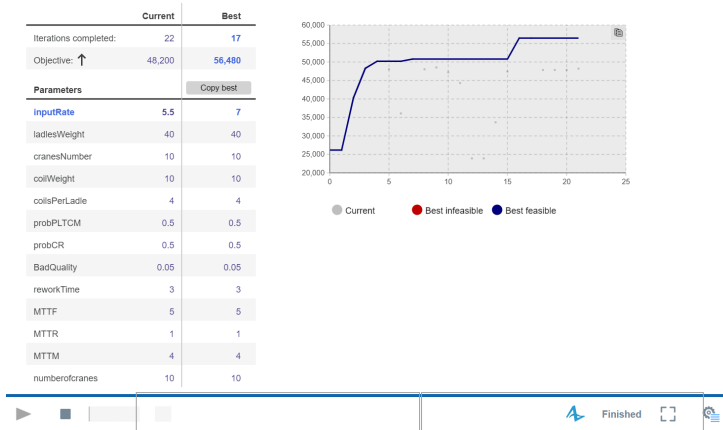
Stop: Stop at specified time  
 Start time: 0 Stop time: 100  
 Start date: 19/11/2023 Stop date: 19/12/2023  
 00:00:00 00:00:00

**Fig.38 Optimization Parameters**

Running the model, we observe that with the best input rate equal to 7, we get a maximum total production of steel equal to 56,480 with 17 iterations.



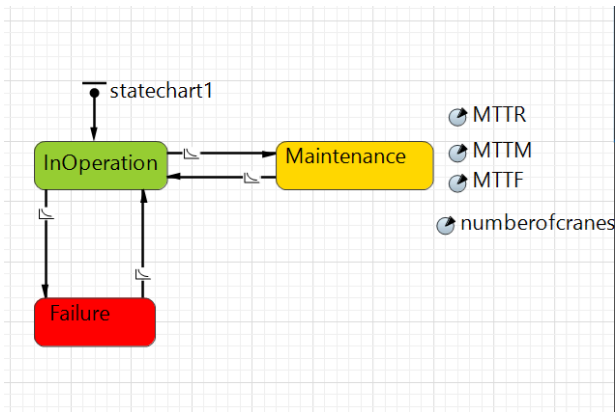
### SteelManufacturingPlant1 : Optimization1



**Fig.39 Optimization Result Model**

### Question 6 (Nada+Alexandra)

We need to simulate a breakdown and maintenance system of only 2 cranes. A breakdown of the crane may happen every 5 days on average and there is maintenance happening regularly every 4 days. We added three states, InOperation, maintenance and failure. We also added the parameters MTTR, MTTM, MTTF and numberofcranes as shown in the figures below. From InOperation to maintenance a transition was added with a rate of  $1/MTTM$  per day and an action of `Cranes.set_capacity(2)`. From maintenance to InOperation it was a rate of  $1/MTTR$  per day. From inOperation to failure a transition with a rate of  $1/MTTF$  per day was added with an action of `Cranes.set_capacity(2)` and lastly the transition from failure to inoperation it was a rate of  $1/MTTR$  per day. As for the states we put the capacity of In Operation as the total number of cranes by setting an action of `Cranes.set_capacity(numberofcranes)`.



Properties

**InOperation - State**

Name:   Show name  Ignore

Fill color:

Entry action:

Exit action:

▶ Description

Properties

**Failure - State**

Name:   Show name  Ignore

Fill color:

Entry action:

Exit action:

▶ Description

Properties

**Maintenance - State**

Name:   Show name  Ignore

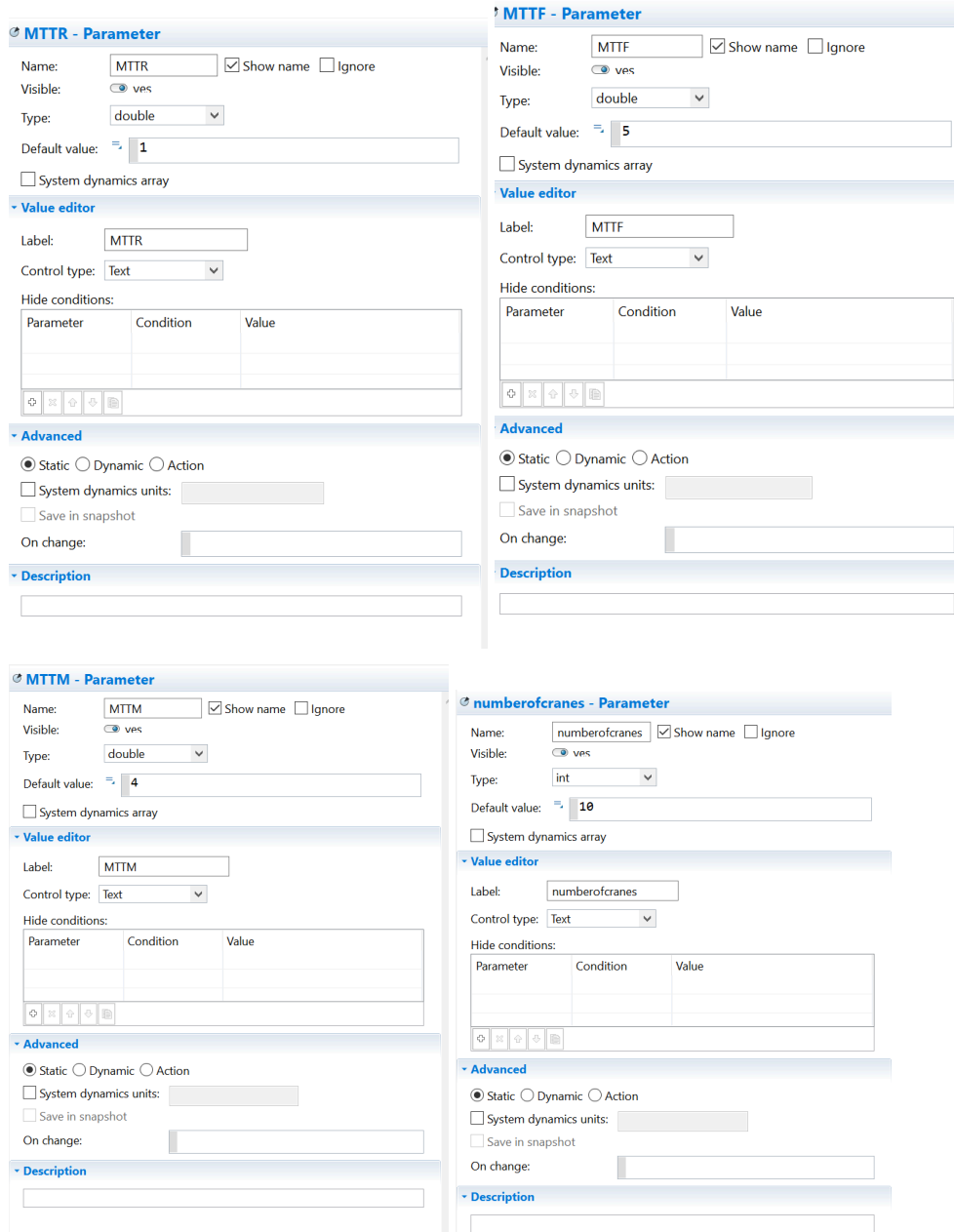
Fill color:

Entry action:

Exit action:

▶ Description

**Fig 40 to Fig 43 State chart representing the maintenance system and each of the states with their specific colors**



**Fig 44 to Fig 47 Parameters**

**Fig 48 (Transition 3)-From InOperation to Maintenance:**

**transition3 - Transition**

Name:   Show name  Ignore

Triggered by:

Rate:

Action:

Guard:

[Description](#)

**Fig 49 (Transition 4)- From Maintenance to InOperation**

**transition4 - Transition**

Name:   Show name  Ignore

Triggered by:

Rate:

Action:

Guard:

[Description](#)

**Fig 50 (Transition 2) from InOperation to Failure:**

Properties  **transition2 - Transition**

Name:   Show name  Ignore

Triggered by:

Rate:

Action:

Guard:

[Description](#)

**Fig 51 (Transition 5) From Failure to InOperation**

**transition5 - Transition**

Name:   Show name  Ignore

Triggered by:

Rate:

Action:

Guard:

[Description](#)

### Question 7 (Hala)

For this question, we need two flows, one for the quality check and the other for reworking. The total amount of slabs are entered into the flow, we use a variable called “Total Slabs” and give it a function “LadleToSlab.count()”, because we want it to count all slabs produced in the steel plant. Only 5% of the total amount of slabs are counted as bad, therefore we set a parameter called “BadQuality” and we set it to be double, and 0.05. Quality check is the inflow of “total slabs\* bad quality”.

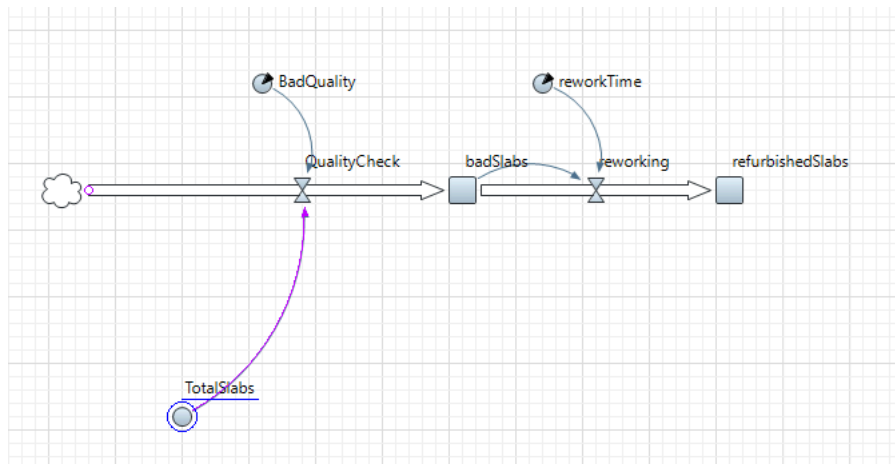


Fig 52 System dynamics model

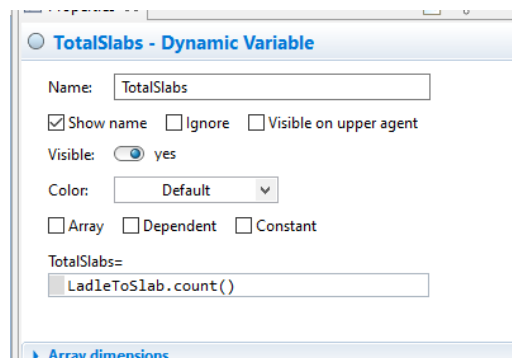


Fig 53 Variable counting slabs

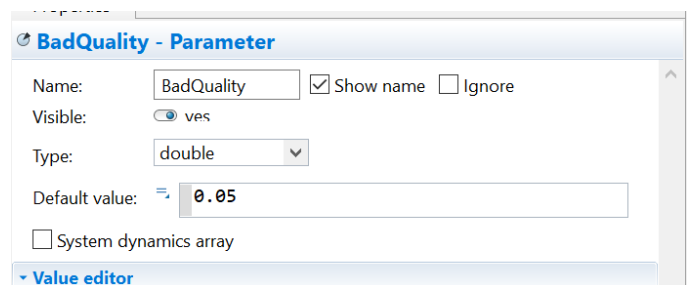
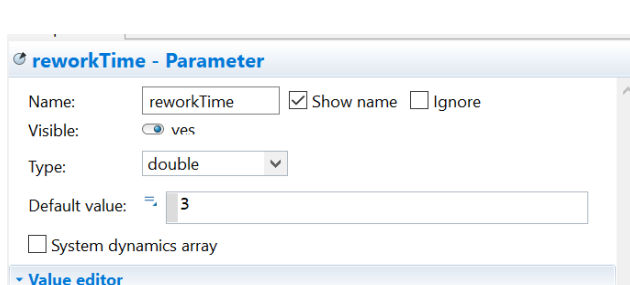
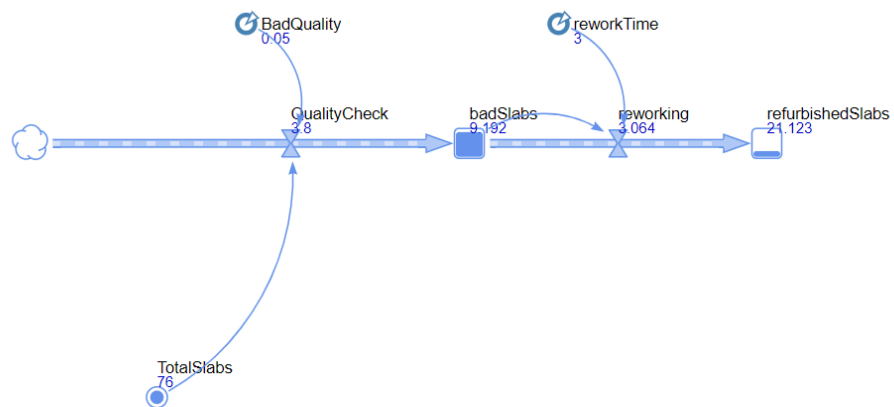


Fig 54 - 55 Fixed Parameters for rework and bad quality

The stock for badSlabs is 0 at the beginning since no bad slabs are entered but as the simulation starts, the stock will start to get filled. The bad slabs are checked and then will go to rework, rework takes 3 hours, so the parameter is set to 3 and our model time units are in hours. Reworking is the inflow of only bad slabs and the time it takes 3 hours to fix them, hence reworking is calculated as “bad slabs/ reworkTime”.

All parameters and the variable were joined by links to the flow.



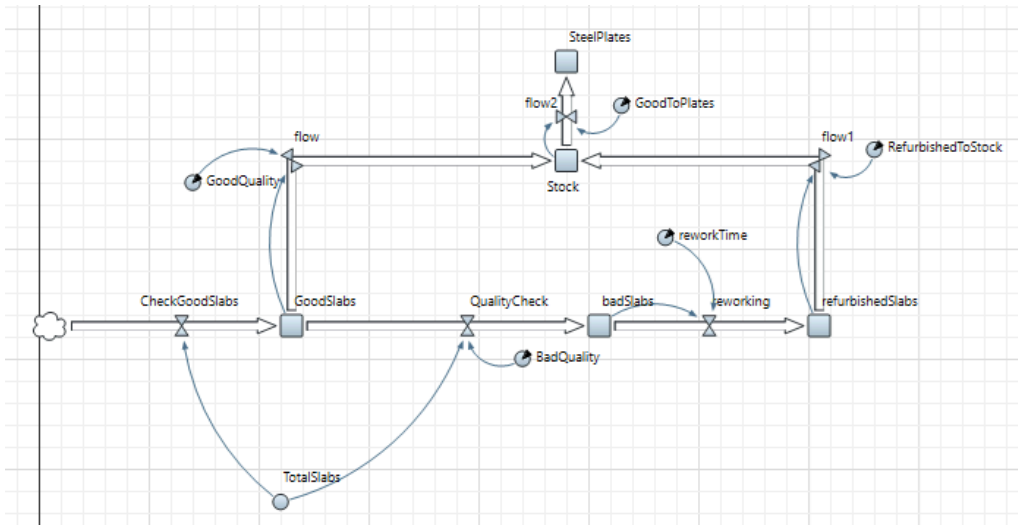
**Fig 56**

**Bonus question (Hala+Joelle):**

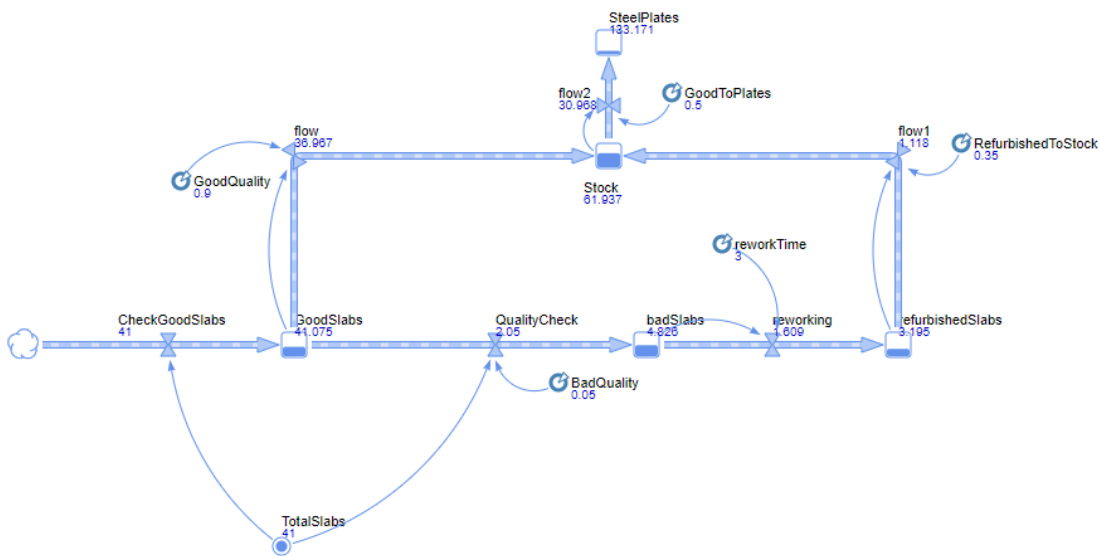
To extend our model with more parameters and feedback loops, we decided to turn slabs to steel plates. We will only need good slabs for that, therefore we will take 90% of the good slabs produced and we will take 35% of the number of refurbished slabs produced and put them in our stock. Only 50% of the stock will be used to produce the plates.

We add a flow connecting before quality check, it will take the total amount of slabs produced and then moves through a flow that takes the 90% as good slabs produced, keeps them in inventory which is the stock here, and then we added another flow after refurbished slabs, the flow will take only 35% of refurbished slabs, the parameter of “RefurbishedToStock” is set to 0.35. The amount is also added to the stock.

Finally we added a final flow from the stock to produce the steel plates, we are not using our whole stock to produce the steel plates but rather only 50% of it, hence we set the parameter “GoodToPlates” to be 0.50.



**Fig. 57 Extended Model**



**Fig. 58 Simulation of Extended Model**

The simulation shows that only 90% of total slabs are considered to be good and will be moved to the stock, the amount of refurbished slabs that have finished with rework and will go to the stock is only 35%. Finally, the model shows that only 50% of the stock will be made into steel plates.

All necessary parameters are equations for the flow of the extended model are provided below

**GoodQuality - Parameter**

Name:   Show name

Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**flow - Flow**

Name:

Show name  Ignore  Visible on upper agent

Visible:  yes

Color:

Array  Dependent  Constant

flow=

**RefurbishedToSlabs - Parameter**

Name:   Show name

Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**flow1 - Flow**

Name:

Show name  Ignore  Visible on upper agent

Visible:  yes

Color:

Array  Dependent  Constant

flow1=

**GoodToPlates - Parameter**

Name:   Show name

Ignore

Visible:  yes

Type:

Default value:

System dynamics array

**flow2 - Flow**

Name:

Show name  Ignore  Visible on upper agent

Visible:  yes

Color:

Array  Dependent  Constant

flow2=

**Fig 59-64 parameters and flows added to the extended model**

### Conclusion (Nada)

In this assignment, we combined all of the previously learned skills in AnyLogic software, from building the model to making state charts. It represents the whole process of steel manufacturing and simulates the organizational process of a steel factory, with all of its main parameters.